

METHOD AND APPARATUS FOR FINE FREQUENCY SYNCHRONIZATION IN
MULTI-CARRIER DEMODULATION SYSTEMS

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FIELD OF THE INVENTION

10 The present invention relates to methods and apparatus for performing a fine frequency synchronization in multi-carrier demodulation systems, and in particular to methods and apparatus for performing a fine frequency synchronization compensating for a carrier frequency deviation from an oscillator frequency in a multi-carrier demodulation system of the

15 type capable of carrying out a differential phase decoding of multi-carrier modulated signals, wherein the signals comprise a plurality of symbols, each symbol being defined by phase differences between simultaneous carriers having different frequencies.

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BACKGROUND OF THE INVENTION

25 In a multi carrier transmission system (MCM, OFDM), the effect of a carrier frequency offset is substantially more considerable than in a single carrier transmission system. MCM is more sensitive to phase noise and frequency offset which occurs as amplitude distortion and inter carrier interference (ICI). The inter carrier interference has the effect that the subcarriers are no longer orthogonal in relation to each other. Frequency offsets occur after power on or also later due to frequency deviation of the oscillators used for downconversion into baseband. Typical accuracies for the frequency of a free running oscillator are about ± 50

30 ppm of the carrier frequency. With a carrier frequency in the S-band of 2.34 GHz, for example, there will be a maximum local oscillator (LO) frequency deviation of above 100 kHz (117.25 kHz). The above named effects result in high requirements on the algorithm used for frequency offset correction.

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DESCRIPTION OF PRIOR ART

5 Most prior art algorithms for frequency synchronization divide frequency correction into two stages. In the first stage, a coarse synchronization is performed. In the second stage, a fine correction can be achieved. A frequently used
10 algorithm for coarse synchronization of the carrier frequency uses a synchronization symbol which has a special spectral pattern in the frequency domain. Such a synchronization symbol is, for example, a CAZAC sequence (CAZAC = Constant Amplitude Zero Autocorrelation). Through comparison, i.e. the correlation, of the power spectrum of the received signal with that of the transmitted signal, the frequency carrier offset can be coarsely estimated. These prior
15 art algorithms all work in the frequency domain. Reference is made, for example, to Ferdinand Claßen, Heinrich Meyr, "Synchronization Algorithms for an OFDM System for Mobile Communication", ITG-Fachtagung 130, Codierung für Quelle,
20 Kanal und Übertragung, pp. 105 - 113, Oct. 26-28, 1994; and Timothy M. Schmidl, Donald C. Cox, "Low-Overhead, Low-Complexity [Burst] Synchronization for OFDM", in Proceedings of the IEEE International Conference on Communication ICC
25 1996, pp. 1301-1306 (1996).

For the coarse synchronization of the carrier frequency, Paul H. Moose, "A Technique for Orthogonal Frequency Division Multiplexing Frequency Offset Correction", IEEE Trans-
30 action On Communications, Vol. 42, No. 10, October 1994, suggest increasing the spacing between the subcarriers such that the subcarrier distance is greater than the maximum frequency difference between the received and transmitted carriers. The subcarrier distance is increased by reducing
35 the number of sample values which are transformed by the Fast Fourier Transform. This corresponds to a reduction of the number of sampling values which are transformed by the Fast Fourier Transform.

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WO 9205646 A relates to methods for the reception of orthogonal frequency division multiplexed signals comprising data which are preferably differentially coded in the direction of the time axis. Phase drift of the demodulated samples from one block to the next is used to indicate the degree of local oscillator frequency error. Phase drift is assessed by multiplying complex values by the complex conjugate of an earlier sample demodulated from the same OFDM carrier and using the resulting measure to steer the local oscillator frequency via a frequency locked loop.

SUMMARY OF THE INVENTION

It is an object of the present invention to provide methods and apparatus for performing a fine frequency synchronization which allow a fine frequency synchronization compensating for a carrier frequency deviation from an oscillator frequency in a MCM transmission system which makes use of MCM signals in which information is differential phase encoded between simultaneous sub-carriers having different frequencies.

In accordance with a first aspect, the present invention provides a method of performing a fine frequency synchronization compensating for a carrier frequency deviation from an oscillator frequency in a multi-carrier demodulation system of the type capable of carrying out a differential phase decoding of multi-carrier modulated signals, the signals comprising a plurality of symbols, each symbol being defined by phase differences between simultaneous carriers having different frequencies, the method comprising the steps of:

determining a phase difference between phases of the same carrier in different symbols;

determining a frequency offset by eliminating phase shift uncertainties related to the transmitted information from

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the phase difference making use of a M-PSK decision device;
and

- 5 performing a feedback correction of the carrier frequency deviation based on the determined frequency offset.

10 In accordance with a second aspect, the present invention provides a method of performing a fine frequency synchronization compensating for a carrier frequency deviation from an oscillator frequency in a multi-carrier demodulation system of the type capable of carrying out a differential phase decoding of multi-carrier modulated signals, the signals comprising a plurality of symbols, each symbol being defined by phase differences between simultaneous carriers having
15 different frequencies, the method comprising the steps of:

- determining respective phases of the same carrier in different symbols;
- 20 eliminating phase shift uncertainties related to the transmitted information from the phases to determine respective phase deviations making use of a M-PSK decision device;

- determining a frequency offset by determining a phase difference between the phase deviations; and
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performing a feedback correction of said carrier frequency deviation based on the determined frequency offset.

- 30 In accordance with a third aspect, the present invention provides an apparatus for performing a fine frequency synchronization compensating for a carrier frequency deviation from an oscillator frequency, for a multi-carrier demodulation system of the type capable of carrying out a differential phase decoding of multi-carrier modulated signals, the
35 signals comprising a plurality of symbols, each symbol being defined by phase differences between simultaneous carriers having different frequencies, the apparatus comprising:

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means for determining a phase difference between phases of the same carrier in different symbols;

5 M-PSK decision device for determining a frequency offset by eliminating phase shift uncertainties related to the transmitted information from the phase difference; and

means for performing a feedback correction of the frequency deviation based on the determined frequency offset.

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In accordance with a fourth aspect, the present invention provides an apparatus for performing a fine frequency synchronization compensating for a carrier frequency deviation from an oscillator frequency, for a multi-carrier demodulation system of the type capable of carrying out a differential phase decoding of multi-carrier modulated signals, said signals comprising a plurality of symbols, each symbol being defined by phase differences between simultaneous carriers having different frequencies, the apparatus comprising:

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means for determining respective phases of the same carrier in different symbols;

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M-PSK decision device for eliminating phase shift uncertainties related to the transmitted information from the phases to determine respective phase deviations;

means for determining a frequency offset by determining a phase difference between the phase deviations; and

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means for performing a feedback correction of the frequency deviation based on the determined frequency offset.

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The present invention relates to methods and apparatus for performing a fine frequency synchronization compensating for a carrier frequency deviation from an oscillator frequency. This fine frequency synchronization is preferably performed after completion of a coarse frequency synchronization, such that the frequency offsets after the coarse frequency syn-

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chronization are smaller than half the sub-carrier distance in the MCM signal. Since the frequency offsets which are to be corrected by the inventive fine frequency synchronization methods and apparatus, a correction of the frequency offsets by using a phase rotation with differential decoding and de-mapping in the time axis can be used. The frequency offsets are detected by determining the frequency differences between time contiguous sub-carrier symbols along the time axis. The frequency error is calculated by measuring the rotation of the I-Q cartesian coordinates of each sub-carrier and, in preferred embodiments, averaging them over all n sub-carriers of a MCM symbol.

Firstly, the phase ambiguity or uncertainty is eliminated by using a M-PSK decision device and correlating the output of the decision device with the input signal for a respective sub-carrier symbol. Thus, the phase offset for a sub-carrier symbol is determined and can be used for restructuring the frequency error in form of a feed-backward structure. Alternatively, the phase offsets of the sub-carrier symbols of one MCM symbol can be averaged over all of the active carriers of a MCM symbol, wherein the averaged phase offset is used to restructure the frequency error.

In accordance with the present invention, the determination of the frequency offset is performed in the frequency domain. The feedback correction in accordance with the inventive fine frequency synchronization is performed in the time domain. To this end, a differential decoder in the time domain is provided in order to detect frequency offsets of sub-carriers on the basis of the phases of timely successive sub-carrier symbols of different MCM symbols.

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BRIEF DESCRIPTION OF THE DRAWINGS

In the following, preferred embodiments of the present invention will be explained in detail on the basis of the drawings enclosed, in which:

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- Figure 1 shows a schematic overview of a MCM transmission system to which the present application can be applied;
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- Figures 2A and 2B show schematic views representing a scheme for differential mapping in the time axis and a scheme for differential mapping in the frequency axis;
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- Figure 3 shows a functional block diagram for performing a differential mapping in the frequency axis;
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- Figure 4 shows a representation of time variation of all sub-carriers in MCM symbols;
- Figure 5 shows a QPSK-constellation for each sub-carrier with a frequency offset;
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- Figure 6 shows a general block diagram illustrating the position of the inventive fine frequency synchronization device in a MCM receiver;
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- Figure 7 shows a block diagram of the fine frequency error detector shown in Figure 6;
- Figure 8 shows a block diagram of a MCM receiver comprising a coarse frequency synchronization unit and a fine frequency synchronization unit;
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- Figure 9 shows a block diagram of a unit for performing a coarse frequency synchronization;
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- Figure 10 shows a schematic view of a reference symbol used for performing a coarse frequency synchronization;
- Figure 11 shows a schematic view of a typical MCM signal having a frame structure;

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5 Figure 12 shows scatter diagrams of the output of an differential de-mapper of a MCM receiver for illustrating the effect of an echo phase offset correction;

Figure 13 shows a schematic block diagram for illustrating the position and the functionality of an echo phase offset correction unit;

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Figure 14 shows a schematic block diagram of a preferred form of an echo phase offset correction device; and

15 Figure 15 shows schematic views for illustrating a projection performed by another echo phase offset correction algorithm.

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DETAILED DESCRIPTION OF THE EMBODIMENTS

Before discussing the present invention in detail, the mode of operation of a MCM transmission system is described referring to figure 1.

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Referring to Figure 1, at 100 a MCM transmitter is shown that substantially corresponds to a prior art MCM transmitter. A description of such a MCM transmitter can be found, for example, in William Y. Zou, Yiyan Wu, "COFDM: AN OVERVIEW", IEEE Transactions on Broadcasting, vol. 41, No. 1, March 1995.

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A data source 102 provides a serial bitstream 104 to the MCM transmitter. The incoming serial bitstream 104 is applied to a bit-carrier mapper 106 which produces a sequence of spectra 108 from the incoming serial bitstream 104. An inverse fast Fourier transform (IFFT) 110 is performed on the sequence of spectra 108 in order to produce a MCM time domain signal 112. The MCM time domain signal forms the useful MCM

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symbol of the MCM time signal. To avoid intersymbol interference (ISI) caused by multipath distortion, a unit 114 is provided for inserting a guard interval of fixed length between adjacent MCM symbols in time. In accordance with a preferred embodiment of the present invention, the last part of the useful MCM symbol is used as the guard interval by placing same in front of the useful symbol. The resulting MCM symbol is shown at 115 in Figure 1 and corresponds to a MCM symbol 160 depicted in Figure 11.

Figure 11 shows the construction of a typical MCM signal having a frame structure. One frame of the MCM time signal is composed of a plurality of MCM symbols 160. Each MCM symbol 160 is formed by an useful symbol 162 and a guard interval 164 associated therewith. As shown in Figure 11, each frame comprises one reference symbol 166. The present invention can advantageously be used with such a MCM signal, however, such a signal structure being not necessary for performing the present invention as long as the transmitted signal comprises a useful portion and at least one reference symbol.

In order to obtain the final frame structure shown in Figure 11, a unit 116 for adding a reference symbol for each predetermined number of MCM symbols is provided.

In accordance with the present invention, the reference symbol is an amplitude modulated bit sequence. Thus, an amplitude modulation of a bit sequence is performed such that the envelope of the amplitude modulated bit sequence defines a reference pattern of the reference symbol. This reference pattern defined by the envelope of the amplitude modulated bit sequence has to be detected when receiving the MCM signal at a MCM receiver. In a preferred embodiment of the present invention, a pseudo random bit sequence having good autocorrelation properties is used as the bit sequence that is amplitude modulated.

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The choice of length and repetition rate of the reference symbol depends on the properties of the channel through which the MCM signal is transmitted, e.g. the coherence time of the channel. In addition, the repetition rate and the length of the reference symbol, in other words the number of useful symbols in each frame, depends on the receiver requirements concerning mean time for initial synchronization and mean time for resynchronization after synchronization loss due to a channel fade.

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The resulting MCM signal having the structure shown at 118 in Figure 1 is applied to the transmitter front end 120. Roughly speaking, at the transmitter front end 120, a digital/analog conversion and an up-converting of the MCM signal is performed. Thereafter, the MCM signal is transmitted through a channel 122.

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Following, the mode of operation of a MCM receiver 130 is shortly described referring to Figure 1. The MCM signal is received at the receiver front end 132. In the receiver front end 132, the MCM signal is down-converted and, furthermore, an analog/digital conversion of the down-converted signal is performed.

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The down-converted MCM signal is provided to a symbol frame/carrier frequency synchronization unit 134.

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A first object of the symbol frame/carrier frequency synchronization unit 134 is to perform a frame synchronization on the basis of the amplitude-modulated reference symbol. This frame synchronization is performed on the basis of a correlation between the amplitude-demodulated reference symbol and a predetermined reference pattern stored in the MCM receiver.

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A second object of the symbol frame/carrier frequency synchronization unit is to perform a coarse frequency synchronization of the MCM signal. To this end, the symbol frame/carrier frequency synchronization unit 134 serves as a

coarse frequency synchronization unit for determining a coarse frequency offset of the carrier frequency caused, for example, by a difference of the frequencies between the local oscillator of the transmitter and the local oscillator of the receiver. The determined frequency is used in order to perform a coarse frequency correction. The mode of operation of the coarse frequency synchronization unit is described in detail referring to Figures 9 and 10 hereinafter.

As described above, the frame synchronization unit 134 determines the location of the reference symbol in the MCM symbol. Based on the determination of the frame synchronization unit 134, a reference symbol extracting unit 136 extracts the framing information, i.e. the reference symbol, from the MCM symbol coming from the receiver front end 132. After the extraction of the reference symbol, the MCM signal is applied to a guard interval removal unit 138. The result of the signal processing performed hereherto in the MCM receiver are the useful MCM symbols.

The useful MCM symbols output from the guard interval removal unit 138 are provided to a fast Fourier transform unit 140 in order to provide a sequence of spectra from the useful symbols. Thereafter, the sequence of spectra is provided to a carrier-bit mapper 142 in which the serial bitstream is recovered. This serial bitstream is provided to a data sink 144.

Next, referring to Figures 2A and 2B, two modes for differential mapping are described. In Figure 2A, a first method of differential mapping along the time axis is shown. As can be seen from Figure 2A, a MCM symbol consists of K sub-carriers. The sub-carriers comprise different frequencies and are, in a preferred embodiment, equally spaced in the frequency axis direction. When using differential mapping along the time axis, one or more bits are encoded into phase and/or amplitude shifts between two sub-carriers of the same center frequency in adjacent MCM symbols. The arrows depicted between the sub-carrier symbols correspond to infor-

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mation encoded in amplitude and/or phase shifts between two sub-carrier symbols.

FIG 2B 27
5 A second method of differential mapping is shown in Figure 2B. The present invention is adapted for MCM transmission system using the mapping scheme shown in Figure 2B. This mapping scheme is based on a differential mapping inside one MCM symbol along the frequency axis. A number of MCM symbols 200 is shown in Figure 2B. Each MCM symbol 200 comprises a
10 number of sub-carrier symbols 202. The arrows 204 in Figure 2B illustrate information encoded between two sub-carrier symbols 202. As can be seen from the arrows 204, this mapping scheme is based on a differential mapping within one MCM symbol along the frequency axis direction.

15 In the embodiment shown in Figure 2B, the first sub-carrier ($k=0$) in an MCM symbol 200 is used as a reference sub-carrier 206 (shaded) such that information is encoded between the reference sub-carrier and the first active carrier
20 208. The other information of a MCM symbol 200 is encoded between active carriers, respectively.

Thus, for every MCM symbol an absolute phase reference exists. In accordance with Figure 2B, this absolute phase reference is supplied by a reference symbol inserted into every
25 MCM symbol ($k=0$). The reference symbol can either have a constant phase for all MCM symbols or a phase that varies from MCM symbol to MCM symbol. A varying phase can be obtained by replicating the phase from the last subcarrier of
30 the MCM symbol preceding in time.

In Figure 3 a preferred embodiment of a device for performing a differential mapping along the frequency axis is shown. Referring to Figure 3, assembly of MCM symbols in the
35 frequency domain using differential mapping along the frequency axis according to the present invention is described.

Figure 3 shows the assembly of one MCM symbol with the following parameters:

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NFFT designates the number of complex coefficients of the discrete Fourier transform, number of subcarriers respectively.

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K designates the number of active carriers. The reference carrier is not included in the count for K.

10 According to Figure 3, a quadrature phase shift keying (QPSK) is used for mapping the bitstream onto the complex symbols. However, other M-ary mapping schemes (MPSK) like 2-PSK, 8-PSK, 16-QAM, 16-APSK, 64-APSK etc. are possible.

15 Furthermore, for ease of filtering and minimization of aliasing effects some subcarriers are not used for encoding information in the device shown in Figure 3. These subcarriers, which are set to zero, constitute the so-called guard bands on the upper and lower edges of the MCM signal spectrum.

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At the input of the mapping device shown in Figure 3, complex signal pairs $b_0[k]$, $b_1[k]$ of an input bitstream are received. K complex signal pairs are assembled in order to form one MCM symbol. The signal pairs are encoded into the K differential phase shifts $\phi[k]$ needed for assembly of one MCM symbol. In this embodiment, mapping from Bits to the 0, 90, 180 and 270 degrees phase shifts is performed using Gray Mapping in a quadrature phase shift keying device 220.

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30 Gray mapping is used to prevent that differential detection phase errors smaller than 135 degrees cause double bit errors at the receiver.

35 Differential phase encoding of the K phases is performed in a differential phase encoder 222. At this stage of processing, the K phases $\phi[k]$ generated by the QPSK Gray mapper are differentially encoded. In principal, a feedback loop 224 calculates a cumulative sum over all K phases. As starting point for the first computation ($k = 0$) the phase of the

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reference carrier 226 is used. A switch 228 is provided in order to provide either the absolute phase of the reference subcarrier 226 or the phase information encoded onto the preceding (i.e. z^{-1} , where z^{-1} denotes the unit delay operator) subcarrier to a summing point 230. At the output of the differential phase encoder 222, the phase information $\theta[k]$ with which the respective subcarriers are to be encoded is provided. In preferred embodiments of the present invention, the subcarriers of a MCM symbol are equally spaced in the frequency axis direction.

The output of the differential phase encoder 222 is connected to a unit 232 for generating complex subcarrier symbols using the phase information $\theta[k]$. To this end, the K differentially encoded phases are converted to complex symbols by multiplication with

$$\text{factor} * e^{j[2\pi(\theta[k] + \text{PHI})]} \quad (\text{Eq.1})$$

wherein factor designates a scale factor and PHI designates an additional angle. The scale factor and the additional angle PHI are optional. By choosing $\text{PHI} = 45^\circ$ a rotated DQPSK signal constellation can be obtained.

Finally, assembly of a MCM symbol is effected in an assembling unit 234. One MCM symbol comprising N_{FFT} subcarriers is assembled from $N_{\text{FFT}} - K - 1$ guard band symbols which are "zero", one reference subcarrier symbol and K DQPSK subcarrier symbols. Thus, the assembled MCM symbol 200 is composed of K complex values containing the encoded information, two guard bands at both sides of the N_{FFT} complex values and a reference subcarrier symbol.

The MCM symbol has been assembled in the frequency domain. For transformation into the time domain an inverse discrete Fourier transform (IDFT) of the output of the assembling unit 234 is performed by a transformator 236. In preferred embodiments of the present invention, the transformator 236 is adapted to perform a fast Fourier transform (FFT).

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tion which can be performed by the symbol frame/carrier frequency synchronization unit 134 are described hereinafter referring to Figures 9 and 10 after having described the fine frequency synchronization in accordance with the present invention.

with the fine frequency synchronization in accordance with the present invention frequency offsets which are smaller than half the sub-carrier distance can be corrected. Since the frequency offsets are low and equal for all sub-carriers the problem of fine frequency synchronization is reduced to sub-carrier level. Figure 4 is a schematical view of MCM symbols 200 in the time-frequency plane. Each MCM symbol 200 consists of 432 sub-carrier symbols C_1 to C_{432} . The MCM symbols are arranged along the time axis, the first MCM symbol 200 shown in Figure 4 having associated therewith a time T_1 , the next MCM symbol having associated therewith a time T_2 and so on. In accordance with a preferred embodiment of the present invention, the fine frequency synchronization is based on a phase rotation which is derived from the same sub-carrier of two MCM symbols which are adjacent in the time axis direction, for example C_1/T_1 and C_1/T_2 .

In the following, the present invention is described referring to QPSK mapping (QPSK = Quadrature Phase Shift Keying). However, it is obvious that the present invention can be applied to any MPSK mapping, wherein M designates the number of phase states used for encoding, for example 2, 4, 8, 16

Figure 5 represents a complex coordinate system showing a QPSK constellation for each sub-carrier with frequency offset. The four possible phase positions of a first MCM symbol, MCM-symbol-1 are shown at 300. Changing from the sub-carrier (sub-carrier n) of this MCM symbol to the same sub-carrier of the next MCM symbol, MCM-symbol-2, the position in the QPSK constellation will be unchanged in case there is no frequency offset. If a frequency offset is present, which is smaller than half the distance between sub-carriers, as

mentioned above, this frequency offset causes a phase rotation of the QPSK constellation of MCM-symbol-2 compared with MCM-symbol-1. The new QPSK constellation, that is the four possible phase positions for the subject sub-carrier of MCM-symbol-2 are shown at 302 in Figure 5. This phase rotation θ can be derived from the following equation:

$$C_n(kT_{MCM}) = e^{j2\pi f_{offset}T_{MCM}} C_n((k-1)T_{MCM})$$
$$\theta = 2\pi f_{offset}T_{MCM} \quad (\text{Eq. 2})$$

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C_n designates the QPSK constellation of a sub-carrier n in a MCM symbol. n is an index running from 1 to the number of active sub-carriers in the MCM symbol. Information regarding the frequency offset is contained in the term $e^{j2\pi f_{offset}T_{MCM}}$ of equation 2. This frequency offset is identical for all sub-carriers. Therefore, the phase rotation θ is identical for all sub-carriers as well. Thus, averaging overall sub-carrier of a MCM symbol can be performed.

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Figure 6 shows a block diagram of a MCM receiver in which the present invention is implemented. An analog/digital converter 310 is provided in order to perform an analog/digital conversion of a down-converted signal received at the receiver front end 132 (Figure 1). The output of the analog/digital converter 310 is applied to a low path filter and decimator unit 312. The low path filter is an impulse forming filter which is identical to an impulse forming filter in the MCM transmitter. In the decimator, the signal is sampled at the MCM symbol frequency. As described above referring to Figure 1, guard intervals in the MCM signal are removed by a guard interval removal unit 132. Guard intervals are inserted between two MCM symbols in the MCM transmitter in order to avoid intersymbol interference caused by channel memory.

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The output of the guard interval removal unit 132 is applied to a MCM demodulator 314 which corresponds to the fast Fourier transformator 140 shown in Figure 1. Following the MCM

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demodulator 314 a differential decoding unit 316 and a demapping unit 318 are provided. In the differential decoding unit 316, phase information is recovered using differential decoding. In the demapping unit 318, demapping along the frequency axis direction is performed in order to reconstruct a binary signal from the complex signal input into the demapping unit 318.

10 The output of the MCM demodulator 314 is also applied to fine frequency error detector 320. The fine frequency error detector 320 produces an frequency error signal from the output of the MCM demodulator. In the depicted embodiment, the output of the fine frequency error detector 320 is applied to a numerical controlled oscillator 322 via a loop filter 324. The loop filter 324 is a low pass filter for filtering superimposed interference portions of a higher frequency from the slowly varying error signal. The numerical controlled oscillator 322 produces a carrier signal on the basis of the filtered error signal. The carrier signal produced by the numerical controlled oscillator 322 is used for a frequency correction which is performed by making use of a complex multiplier 326. The inputs to the complex multiplier 326 are the output of the low pass filter and decimator unit 312 and the output of the numerical controlled oscillator 322.

A description of a preferred embodiment of the fine frequency error detector 320 is given hereinafter referring to Figure 7.

30 The fine frequency error detector 320 comprises a differential detector in the time axis 330. The output of the MCM demodulator 314, i.e. the FFT output (FFT = Fast Fourier Transform) is applied to the input of the differential detector 330 which performs a differential detection in the time axis in order to derive information on a frequency offset from the same sub-carrier of two subsequently arriving MCM symbols. In the embodiment shown in Figure 7, the number of active sub-carriers is 432. Thus, the differential detec-

tor 330 performs a correlation between the first and the 433rd sample. The first sample is associated with MCM-symbol-1 (Figure 5), whereas the 433rd sample is associated with MCM-symbol-2 (Figure 5). However, both these samples are associated with the same sub-carrier.

To this end, the input signal Y_k is applied to a z^{-1} -block 332 and thereafter to a unit 334 in order to form the complex conjugate of the output of the z^{-1} -block 332. A complex multiplier 336 is provided in order to multiply the output of the unit 334 by the input signal Y_k . The output of the multiplier 336 is a signal Z_k .

The function of the differential detector 330 can be expressed as follows:

$$Z_k = Y_{k+K} \cdot Y_k^* \quad (\text{Eq. 3})$$

$$Y = [Y_1, Y_2, \dots, Y_k, \dots] \quad (\text{Eq. 4})$$

$$Y = [C_1 / T_1, C_2 / T_1, \dots, C_{432} / T_1, C_1 / T_2, \dots] \quad (\text{Eq. 5})$$

Y_k designates the output of the MCM modulator 314, i.e. the input to the differential detector 330, at a time k . Z_k designates the output of the differential detector 330. K designates the number of active carriers.

J45857 The output Z_k of the differential detector 330 contains a M -fold uncertainty corresponding to codeable phase shifts. In case of the QPSK this M -fold uncertainty is a 4-fold uncertainty, i.e. 0° , 90° , 180° and 270° . This phase shift uncertainty is eliminated from Z_k making use of a M -PSK decision device 340. Such decision devices are known in the art and, therefore, have not to be described here in detail. The output of the decision device 340 $(\hat{a}_k)^*$ represents the complex conjugate of the codeable phase shift decided by the decision device 340. This output of the decision device 340 is

correlated with the output of the differential detector 330 by performing a complex multiplication using a multiplier 342.

The output the multiplier 342 represents the phase offset for the respective sub-carriers. This phase offsets for the respective sub-carriers are averaged over one MCM symbol in an averaging unit 344 in accordance with a preferred embodiment of the present invention. The output of the averaging units 344 represent the output of the fine frequency error detector 320.

The mathematical description for this procedure is as follows:

$$f_{offset} = \frac{1}{2\pi K T_{MCM}} \arg \left\{ \sum_{n=1}^K Z_n \cdot \left(\hat{a}_n \right)^* \right\} \quad (\text{Eq. 6})$$

In accordance with preferred embodiments of the present invention, the frequency control loop has a backward structure. In the embodiment shown in Figure 6, the feedback loop is connected between the output of the MCM demodulator 314 and the input of the guard interval removal unit 132.

In Figure 8, a block diagram of a MCM receiver comprising a coarse frequency correction unit 350 and a fine frequency correction unit as described above is shown. As shown in Figure 8, a common complex multiplier 326 can be used in order to perform the coarse frequency correction and the fine frequency correction. As shown in Figure 8, the multiplier 326 can be provided preceding the low pass filter and decimator unit 312. Depending on the position of the multiplier 326, a hold unit has to be provided in the fine frequency synchronization feedback loop. In an alternative embodiment, it is possible to use two separate multipliers for the coarse frequency correction and for the fine frequency correction. In such a case, the multiplier for the coarse frequency correction will be arranged preceding the low path

filter and decimator unit, whereas the multiplier for the fine frequency correction will be arranged following the low path filter and decimator unit.

- 5 Following, preferred embodiments for implementing a coarse frequency synchronization will be described referring to Figures 9 and 10.

10 As it is shown in Figure 9, the output of the receiver front end 132 is connected to an analog/digital converter 310. The down-converted MCM signal is sampled at the output of the analog/digital converter 310 and is applied to a frame/timing synchronization unit 360. In a preferred embodiment, a fast running automatic gain control (AGC) (not
15 shown) is provided preceding the frame/timing synchronization unit in order to eliminate fast channel fluctuations. The fast AGC is used in addition to the normally slow AGC in the signal path, in the case of transmission over a multipath channel with long channel impulse response and frequency selective fading. The fast AGC adjusts the average
20 amplitude range of the signal to the known average amplitude of the reference symbol.

25 As described above, the frame/timing synchronization unit uses the amplitude-modulated sequence in the received signal in order to extract the framing information from the MCM signal and further to remove the guard intervals therefrom. After the frame/timing synchronization unit 360 it follows a coarse frequency synchronization unit 362 which estimates a
30 coarse frequency offset based on the amplitude-modulated sequence of the reference symbol of the MCM signal. In the coarse frequency synchronization unit 362, a frequency offset of the carrier frequency with respect to the oscillator frequency in the MCM receiver is determined in order to perform a frequency offset correction in a block 364. This frequency offset correction in block 364 is performed by a complex multiplication.
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Fig 9

The output of the frequency offset correction block 364 is applied to the MCM demodulator 366 formed by the Fast Fourier Transformator 140 and the carrier-bit mapper 142 shown in Figure 1.

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In order to perform the coarse frequency synchronization described herein, an amplitude-demodulation has to be performed on a preprocessed MCM signal. The preprocessing may be, for example, the down-conversion and the analog/digital conversion of the MCM signal. The result of the amplitude-demodulation of the preprocessed MCM signal is an envelope representing the amplitude of the MCM signal.

For the amplitude demodulation a simple $\alpha_{\max+}$ $\beta_{\min-}$ method can be used. This method is described for example in Palacherla A.: DSP- μ P Routine Computes Magnitude, EDN, October 26, 1989; and Adams, W. T., and Bradley, J.: Magnitude Approximations for Microprocessor Implementation, IEEE Micro, Vol. 3, No. 5, October 1983.

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It is clear that amplitude determining methods different from the described $\alpha_{\max+}$ $\beta_{\min-}$ method can be used. For simplification, it is possible to reduce the amplitude calculation to a detection as to whether the current amplitude is above or below the average amplitude. The output signal then consists of a -1/+1 sequence which can be used to determine a coarse frequency offset by performing a correlation. This correlation can easily be performed using a simple integrated circuit (IC).

30

In addition, an oversampling of the signal received at the RF front end can be performed. For example, the received signal can be expressed with two times oversampling.

35 In accordance with a first embodiment, a carrier frequency offset of the MCM signal from an oscillator frequency in the MCM receiver is determined by correlating the envelope obtained by performing the amplitude-demodulation as described above with a predetermined reference pattern.

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In case there is no frequency offset, the received reference symbol $r(k)$ will be:

$$r(k) = S_{AM}(k) + n(k) \quad (\text{Eq.7})$$

wherein $n(k)$ designates "additive Gaussian noise" and S_{AM} denotes the AM sequence which has been sent. In order to simplify the calculation the additive Gaussian noise can be neglected. It follows:

$$r(k) \cong S_{AM}(k) \quad (\text{Eq.8})$$

In case a constant frequency offset Δf is present, the received signal will be:

$$\tilde{r}(k) = S_{AM}(k) \cdot e^{j2\pi\Delta f k T_{MCM}} \quad (\text{Eq.9})$$

Information regarding the frequency offset is derived from the correlation of the received signal $\tilde{r}(k)$ with the AM sequence S_{AM} which is known in the receiver:

$$\sum_{k=1}^{\frac{L}{2}} \tilde{r}(k) \cdot S_{AM}^*(k) = \sum_{k=1}^{\frac{L}{2}} |S_{AM}(k)|^2 e^{j2\pi\Delta f k T_{MCM}} \quad (\text{Eq.10})$$

Thus, the frequency offset is:

$$\Delta f = \frac{1}{2\pi T_{MCM}} \arg \left(\sum_{k=1}^{\frac{L}{2}} r(k) \cdot S_{AM}^*(k) \right) - \frac{1}{2\pi T_{MCM}} \arg \left(\sum_{k=1}^{\frac{L}{2}} |S_{AM}(k)|^2 \right) \quad (\text{Eq.11})$$

Since the argument of $|S_{AM}(k)|^2$ is zero the frequency offset is:

$$\Delta f = \frac{1}{2\pi T_{MCM}} \arg \left(\sum_{k=1}^{\frac{L}{2}} \tilde{r}(k) \cdot S_{AM}^* \right) \quad (\text{Eq.12})$$

In accordance with a second embodiment of the coarse frequency synchronization algorithm, a reference symbol comprising at least two identical sequences 370 as shown in Figure 10 is used. Figure 10 shows the reference symbol of a MCM signal having two identical sequences 370 of a length of L/2 each. L designates the number of values of the two sequences 370 of the reference symbol.

As shown in Figure 10, within the amplitude-modulated sequence, there are at least two identical sections devoted to the coarse frequency synchronization. Two such sections, each containing L/2 samples, are shown at the end of the amplitude-modulated sequence in Figure 10. The amplitude-modulated sequence contains a large number of samples. For a non-ambiguous observation of the phase, only enough samples to contain a phase rotation of 2π should be used. This number is defined as L/2 in Figure 10.

Following, a mathematical derivation of the determination of a carrier frequency deviation is presented. In accordance with Figure 10, the following equation applies for the two identical sequences 370:

$$s\left(0 < k \leq \frac{L}{2}\right) \equiv s\left(\frac{L}{2} < k \leq L\right) \quad (\text{Eq.13})$$

If no frequency offset is present, the following equation 14 will be met by the received signal:

$$r\left(k + \frac{L}{2}\right) \equiv r(k) \quad 0 < k \leq \frac{L}{2} \quad (\text{Eq.14})$$

$r(k)$ designates the values of the identical sequences. k is an index from one to $L/2$ for the respective samples.

If there is a frequency offset of, for example, Δf , the received signal is:

$$\tilde{r}(k) = r(k) \cdot e^{j2\pi\Delta f k T_{MCM}} \quad (\text{Eq. 15})$$

$$\tilde{r}\left(k + \frac{L}{2}\right) = r(k) \cdot e^{j2\pi\Delta f \left(k + \frac{L}{2}\right) T_{MCM}} \quad (\text{Eq. 16})$$

10

$r(k)$ designates sample values of the received portion which are based on the identical sequences. Information regarding the frequency offset is derived from the correlation of the received signal $\tilde{r}(k + L/2)$ with the received signal $\tilde{r}(k)$.

15 This correlation is given by the following equation:

$$\sum_{k=1}^{\frac{L}{2}} \tilde{r}^*\left(k + \frac{L}{2}\right) \tilde{r}(k) = \sum_{k=1}^{\frac{L}{2}} |r(k)|^2 e^{-j2\pi\Delta f \frac{L}{2} T_{MCM}} \quad (\text{Eq. 17})$$

20 \tilde{r}^* designates the complex conjugate of the sample values of the portion mentioned above.

Thus, the frequency offset is

$$\Delta f = \frac{1}{2\pi \frac{L}{2} T_{MCM}} \arg \left(\sum_{k=1}^{\frac{L}{2}} \tilde{r}\left(k + \frac{L}{2}\right) \cdot \tilde{r}^*(k) \right) - \frac{1}{2\pi \frac{L}{2} T_{MCM}} \arg \left(\sum_{k=1}^{\frac{L}{2}} |\tilde{r}(k)|^2 \right) \quad (\text{Eq. 18})$$

25

Since the argument of $|\tilde{r}(k)|^2$ equals zero, the frequency offset becomes

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$$\Delta f = \frac{1}{2\pi \frac{L}{2} T_{MCM}} \arg \left(\sum_{k=1}^{\frac{L}{2}} \tilde{r} \left(k + \frac{L}{2} \right) \cdot \tilde{r}^*(k) \right) \quad (\text{Eq.19})$$

Thus, it is clear that in both embodiments, described above, the frequency position of the maximum of the resulting output of the correlation determines the estimated value of the offset carrier. Furthermore, as it is also shown in Figure 9, the correction is performed in a feed forward structure.

10 In case of a channel with strong reflections, for example due to a high building density, the correlations described above might be insufficient for obtaining a suitable coarse frequency synchronization. Therefore, in accordance with a third embodiment of the present invention, corresponding values of the two portions which are correlated in accordance with a second embodiment, can be weighting with corresponding values of stored predetermined reference patterns corresponding to said two identical sequences of the reference symbol. This weighting can maximize the probability of correctly determining the frequency offset. The mathematical description of this weighting is as follows:

$$\Delta f = \frac{1}{2\pi \frac{L}{2} T_{MCM}} \arg \left(\sum_{k=1}^{\frac{L}{2}} \left[\tilde{r} \left(k + \frac{L}{2} \right) \cdot \tilde{r}^*(k) \right] \cdot \left[S_{AM}(k) S_{AM}^* \left(k + \frac{L}{2} \right) \right] \right) \quad (\text{Eq.20})$$

25 S_{AM} designates the amplitude-modulated sequence which is known in the receiver, and S_{AM}^* designates the complex conjugate thereof.

30 If the above correlations are calculated in the frequency domain, the amount of

$$\sum_{k=1}^{\frac{L}{2}} \left[\tilde{r} \left(k + \frac{L}{2} \right) \cdot \tilde{r}^*(k) \right] \cdot \left[S_{AM}(k) S_{AM}^* \left(k + \frac{L}{2} \right) \right] \quad (\text{Eq.21})$$

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is used rather than the argument. This amount is maximized as a function of a frequency correction. The position of the maximum determines the estimation of the frequency deviation. As mentioned above, the correction is performed in a feed forward structure.

Preferred embodiments for performing an echo phase offset correction when using a differential mapping in the frequency axis will be described hereinafter referring to Figures 12 to 15.

Systematic phase shifts stemming from echoes in multipath environments may occur between subcarriers in the same MCM symbol. This phase offsets can cause bit errors when demodulating the MCM symbol at the receiver. Thus, it is preferred to make use of an algorithm to correct the systematic phase shifts stemming from echoes in multipath environments.

In Figure 12, scatter diagrams at the output of a differential demapper of a MCM receiver are shown. As can be seen from the left part of Figure 12, systematic phase shifts between subcarriers in the same MCM symbol cause a rotation of the demodulated phase shifts with respect to the axis of the complex coordinate system. In the right part of Figure 12, the demodulated phase shifts after having performed an echo phase offset correction are depicted. Now, the positions of the signal points are substantially on the axis of the complex coordinate system. These positions correspond to the modulated phase shifts of 0° , 90° , 180° and 270° , respectively.

An echo phase offset correction algorithm (EPOC algorithm) must calculate the echo induced phase offset from the signal space constellation following the differential demodulation and subsequently correct this phase offset.

For illustration purposes, one may think of the simplest algorithm possible which eliminates the symbol phase before

computing the mean of all phases of the subcarriers. To illustrate the effect of such an EPOC algorithm, reference is made to the two scatter diagrams of subcarriers symbols contained in one MCM symbol in Figure 12. This scatter diagrams
5 have been obtained as result of an MCM simulation. For the simulation a channel has been used which might typically show up in single frequency networks. The echoes of this channel stretched to the limits of the MCM guard interval. The guard interval was chosen to be 25% of the MCM symbol
10 duration in this case.

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Figure 13 represents a block diagram for illustrating the position and the functionality of an echo phase offset correction device in a MCM receiver. The signal of a MCM transmitter is transmitted through the channel 122 (Figures 1 and 13) and received at the receiver frontend 132 of the MCM receiver. The signal processing between the receiver frontend and the fast Fourier transformator 140 has been omitted in
15 Figure 13. The output of the fast Fourier transformator is applied to the de-mapper, which performs a differential de-mapping along the frequency axis. The output of the de-mapper are the respective phase shifts for the subcarriers. The phase offsets of this phase shifts which are caused by
20 echoes in multipath environments are visualized by a block 400 in Figure 13 which shows an example of a scatter diagram of the subcarrier symbols without an echo phase offset correction.

30 The output of the de-mapper 142 is applied to the input of an echo phase offset correction device 402. The echo phase offset correction device 402 uses an EPOC algorithm in order to eliminate echo phase offsets in the output of the de-mapper 142. The result is shown in block 404 of Figure 13,
35 i.e. only the encoded phase shifts, 0° , 90° , 180° or 270° are present at the output of the correction device 402. The output of the correction device 402 forms the signal for the metric calculation which is performed in order to recover the bitstream representing the transmitted information.

FIG 13 B13 A first embodiment of an EPOC algorithm and a device for performing same is now described referring to Figure 14.

5 The first embodiment of an EPOC algorithm starts from the assumption that every received differentially decoded complex symbol is rotated by an angle due to echoes in the multipath channel. For the subcarriers equal spacing in frequency is assumed since this represents a preferred embodiment. If the subcarriers were not equally spaced in frequency, a correction factor would have to be introduced into the EPOC algorithm.

10 Figure 14 shows the correction device 402 (Figure 13) for performing the first embodiment of an EPOC algorithm.

15 From the output of the de-mapper 142 which contains an echo phase offset as shown for example in the left part of Figure 12, the phase shifts related to transmitted information must first be discarded. To this end, the output of the de-mapper 142 is applied to a discarding unit 500. In case of a DQPSK mapping, the discarding unit can perform a " $(.)^4$ " operation. The unit 500 projects all received symbols into the first quadrant. Therefore, the phase shifts related to transmitted information is eliminated from the phase shifts representing the subcarrier symbols. The same effect could be reached with a modulo-4 operation.

20 Having eliminated the information related symbol phases in unit 500, the first approach to obtain an estimation would be to simply compute the mean value over all symbol phases of one MCM symbol. However, it is preferred to perform a threshold decision before determining the mean value over all symbol phases of one MCM symbol. Due to Rayleigh fading some of the received symbols may contribute unreliable information to the determination of the echo phase offset. Therefore, depending on the absolute value of a symbol, a threshold decision is performed in order to determine

whether the symbol should contribute to the estimate of the phase offset or not.

Thus, in the embodiment shown in Figure 14, a threshold decision unit 510 is included. Following the unit 500 the absolute value and the argument of a differentially decoded symbol is computed in respective computing units 512 and 514. Depending on the absolute value of a respective symbol, a control signal is derived. This control signal is compared with a threshold value in a decision circuit 516. If the absolute value, i.e. the control signal thereof, is smaller than a certain threshold, the decision circuit 516 replaces the angle value going into the averaging operation by a value equal to zero. To this end, a switch is provided in order to disconnect the output of the argument computing unit 514 from the input of the further processing stage and connects the input of the further processing stage with a unit 518 providing a constant output of "zero".

An averaging unit 520 is provided in order to calculate a mean value based on the phase offsets φ_i determined for the individual subcarrier symbols of a MCM symbol as follows:

$$\bar{\varphi} = 1 / K \sum_{i=1}^K \varphi_i \quad (\text{Eq.22})$$

In the averaging unit 520, summation over K summands is performed. The output of the averaging unit 520 is provided to a hold unit 522 which holds the output of the averaging unit 520 K times. The output of the hold unit 522 is connected with a phase rotation unit 524 which performs the correction of the phase offsets of the K complex signal points on the basis of the mean value $\bar{\varphi}$.

The phase rotation unit 524 performs the correction of the phase offsets by making use of the following equation:

$$v'_k = v_k \cdot e^{-j\bar{\varphi}} \quad (\text{Eq.23})$$

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In this equation, v'_k designates the K phase corrected differentially decoded symbols for input into the soft-metric calculation, whereas v_k designates the input symbols. As long as a channel which is quasi stationary during the duration of one MCM symbols can be assumed, using the mean value over all subcarriers of one MCM symbol will provide correct results.

10 A buffer unit 527 may be provided in order to buffer the complex signal points until the mean value of the phase offsets for one MCM symbol is determined. The output of the phase rotation unit 524 is applied to the further processing stage 526 for performing the soft-metric calculation.

15 With respect to the results of the above echo phase offset correction, reference is made again to Figure 12. The two plots stem from a simulation which included the first embodiment of an echo phase offset correction algorithm described above. At the instant of the scatter diagram snapshot shown in the left part of Figure 12, the channel obviously distorted the constellation in such a way, that a simple angle rotation is a valid assumption. As shown in the right part of Figure 12, the signal constellation can be rotated back to the axis by applying the determined mean value for the rotation of the differentially detected symbols.

A second embodiment of an echo phase offset correction algorithm is described hereinafter. This second embodiment can be preferably used in connection with multipath channels that have up to two strong path echoes. The algorithm of the second embodiment is more complex than the algorithm of the first embodiment.

35 What follows is a mathematical derivation of the second embodiment of a method for echo phase offset correction. The following assumptions can be made in order to ease the explanation of the second embodiment of an EPOC algorithm.

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In this embodiment, the guard interval of the MCM signal is assumed to be at least as long as the impulse response $h[q]$, $q = 0, 1, \dots, Q_h-1$ of the multipath channel.

5

At the transmitter every MCM symbol is assembled using frequency axis mapping explained above. The symbol of the reference subcarrier equals 1, i.e. 0 degree phase shift. The optional phase shift PHI equals zero, i.e. the DQPSK signal constellation is not rotated.

10

Using an equation this can be expressed as

$$a_k = a_{k-1} a_k^{inc}$$

15 (Eq.24)

with

k : index $k = 1, 2, \dots, K$ of the active subcarrier;

$$a_k^{inc} = e^{j \frac{\pi}{2} m}$$

20 : complex phase increment symbol; $m=0, 1, 2, 3$ is the QPSK symbol number which is derived from Gray encoding pairs of 2 Bits;

$$a_0 = 1$$

25 : symbol of the reference subcarrier.

At the DFT output of the receiver the decision variables

$$e_k = a_k H_k$$

(Eq.25)

30 are obtained with

$$H_k = \sum_{i=0}^{Q_h-1} h[i] \cdot e^{-j \frac{2\pi}{K} k i}$$

(Eq.26)

being the DFT of the channel impulse response $h[q]$ at position k .

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with $|a_k|^2 = 1$ the differential demodulation yields

$$v_k = e_k \cdot e_{k-1}^* = a_k^{inc} H_k H_{k-1}^* \quad (\text{Eq.27})$$

5 For the receiver an additional phase term φ_k is introduced, which shall be used to correct the systematic phase offset caused by the channel. Therefore, the final decision variable at the receiver is

$$10 \quad v'_k = v_k \cdot e^{j\varphi_k} = a_k^{inc} \cdot e^{j\varphi_k} \cdot H_k \cdot H_{k-1}^* \quad (\text{Eq.28})$$

As can be seen from the Equation 28, the useful information a_k^{inc} is weighted with the product $e^{j\varphi_k} \cdot H_k \cdot H_{k-1}^*$ (rotation and effective transfer function of the channel). This product must be real-valued for an error free detection. Considering this, it is best to choose the rotation angle to equal the negative argument of $H_k \cdot H_{k-1}^*$. To derive the desired algorithm for 2-path channels, the nature of $H_k \cdot H_{k-1}^*$ is investigated in the next section.

It is assumed that the 2-path channel exhibits two echoes with energy content unequal zero, i.e. at least two dominant echoes. This assumption yields the impulse response

$$25 \quad h[q] = c_1 \delta_0[q] + c_2 \delta_0[q - q_0] \quad (\text{Eq.29})$$

with

30 c_1, c_2 : complex coefficients representing the path echoes;
 q_0 : delay of the second path echo with respect to the first path echo;
 δ_0 : Dirac pulse; $\delta_0[k] = 1$ for $k = 0$
 $\delta_0[k] = 0$ else

35

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The channel transfer function is obtained by applying a DFT to Equation 29:

$$H_k = H\left(e^{j\frac{2\pi}{K}k}\right) = c_1 + c_2 \cdot e^{-j\frac{2\pi}{K}kq_0} \quad (\text{Eq. 30})$$

5

With Equation 30 the effective transfer function for differential demodulation along the frequency axis is:

$$\begin{aligned} H_k \cdot H_{k-1}^* &= \left(c_1 + c_2 e^{-j\frac{2\pi}{K}kq_0} \right) \cdot \left(c_1^* + c_2^* e^{+j\frac{2\pi}{K}(k-1)q_0} \right) \\ &= c_a + c_b \cos\left(\frac{\pi}{K} q_0 (2k - 1)\right) \end{aligned} \quad (\text{Eq. 31})$$

10

Assuming a noise free 2-path channel, it can be observed from Equation 31 that the symbols on the receiver side are located on a straight line in case the symbol $1+j0$ has been send (see above assumption). This straight line can be characterized by a point

15

$$c_a = |c_1|^2 + |c_2|^2 \cdot e^{-j\frac{2\pi}{K}q_0} \quad (\text{Eq. 32})$$

20 and the vector

$$c_b = 2c_1c_2^* \cdot e^{-j\frac{\pi}{K}q_0} \quad (\text{Eq. 33})$$

which determines its direction.

25

With the above assumptions, the following geometric derivation can be performed. A more suitable notation for the geometric derivation of the second embodiment of an EPOC algorithm is obtained if the real part of the complex plane is designated as $x = \text{Re}\{z\}$, the imaginary part as $y = \text{Im}\{z\}$, respectively, i.e. $z = x+jy$. With this new notation, the straight line, on which the received symbols will lie in case of a noise-free two-path channel, is

30

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$$f(x) = a + b \cdot x \quad (\text{Eq. 34})$$

with

5

$$a = \text{Im}\{c_a\} - \frac{\text{Re}\{c_a\}}{\text{Re}\{c_b\}} \cdot \text{Im}\{c_b\} \quad (\text{Eq. 35})$$

and

$$b = - \frac{\text{Im}\{c_a\} - \frac{\text{Re}\{c_a\}}{\text{Re}\{c_b\}} \cdot \text{Im}\{c_b\}}{\text{Re}\{c_a\} - \frac{\text{Im}\{c_a\}}{\text{Im}\{c_b\}} \cdot \text{Re}\{c_b\}} \quad (\text{Eq. 36})$$

Additional noise will spread the symbols around the straight line given by Equations 34 to 36. In this case Equation 36 is the regression curve for the cluster of symbols.

15

For the geometric derivation of the second embodiment of an EPOC algorithm, the angle φ_k from Equation 28 is chosen to be a function of the square distance of the considered symbol from the origin:

20

$$\varphi_k = f_K(|z|^2) \quad (\text{Eq. 37})$$

Equation 37 shows that the complete signal space is distorted (torsion), however, with the distances from the origin being preserved.

25

For the derivation of the algorithm of the second embodiment, $f_K(\cdot)$ has to be determined such that all decision variables v_k (assuming no noise) will come to lie on the real axis:

30

$$\text{Im}\{(x + jf(x)) \cdot e^{jf_K(|z|^2)}\} = 0 \quad (\text{Eq. 38})$$

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Further transformations of Equation 38 lead to a quadratic equation which has to be solved to obtain the solution for φ_k .

- 5 In case of a two-path channel, the echo phase offset correction for a given decision variable v_k is

$$v'_k = v_k \cdot e^{j\varphi_k} \quad (\text{Eq.39})$$

- 10 with

$$\varphi_k = \begin{cases} -a \tan \left(\frac{a + b\sqrt{|v_k|^2(1+b^2) - a^2}}{-ab + \sqrt{|v_k|^2(1+b^2) - a^2}} \right) & \text{for } |v_k|^2 \geq \frac{a^2}{1+b^2} \\ a \tan \left(\frac{1}{b} \right) & \text{for } |v_k|^2 < \frac{a^2}{1+b^2} \end{cases} \quad (\text{Eq.40})$$

- 15 From the two possible solutions of the quadratic equation mentioned above, Equation 40 is the one solution that cannot cause an additional phase shift of 180 degrees.

- 20 The two plots in Figure 15 show the projection of the EPOC algorithm of the second embodiment for one quadrant of the complex plane. Depicted here is the quadratic grid in the sector $|\arg(z)| \leq \pi/4$ and the straight line $y = f(x) = a + b \cdot x$ with $a = -1.0$ and $b = 0.5$ (dotted line). In case of a noise-free channel, all received symbols will lie on this straight line if $1+j0$ was send. The circle shown in the plots determines the boarder line for the two cases of Equation 40. In the left part, Figure 15 shows the situation before the projection, in the right part, Figure 15 shows the situation after applying the projection algorithm.
- 25 By looking on the left part, one can see, that the straight line now lies on the real axis with $2+j0$ being the fix point of the projection. Therefore, it can be concluded that the echo phase offset correction algorithm according to the second embodiment fulfills the design goal.
- 30

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Before the second embodiment of an EPOC algorithm can be applied, the approximation line through the received symbols has to be determined, i.e. the parameters a and b must be estimated. For this purpose, it is assumed that the received symbols lie in sector $|\arg(z)| \leq \pi/4$, if $1+j0$ was sent. If symbols other than $1+j0$ have been sent, a modulo operation can be applied to project all symbols into the desired sector. Proceeding like this prevents the necessity of deciding on the symbols in an early stage and enables averaging over all signal points of one MCM symbol (instead of averaging over only $\frac{1}{4}$ of all signal points).

For the following computation rule for the EPOC algorithm of the second embodiment, x_i is used to denote the real part of the i -th signal point and y_i for its imaginary part, respectively ($i = 1, 2, \dots, K$). Altogether, K values are available for the determination. By choosing the method of least squares, the straight line which has to be determined can be obtained by minimizing

$$(a, b) = \arg \min_{(\tilde{a}, \tilde{b})} \sum_{i=1}^K (y_i - (\tilde{a} + \tilde{b} \cdot x_i))^2 \quad (\text{Eq. 41})$$

The solution for Equation 41 can be found in the laid open literature. It is

$$b = \frac{\sum_{i=1}^K (x_i - \bar{x}) \cdot y_i}{\sum_{i=1}^K (x_i - \bar{x})^2}, \quad a = \bar{y} - \bar{x} \cdot b \quad (\text{Eq. 42})$$

with mean values

$$\bar{x} = \frac{1}{N} \sum_{i=1}^K x_i, \quad \bar{y} = \frac{1}{N} \sum_{i=1}^K y_i \quad (\text{Eq. 43})$$

If necessary, an estimation method with higher robustness can be applied. However, the trade-off will be a much higher computational complexity.

- 5 To avoid problems with the range in which the projection is applicable, the determination of the straight line should be separated into two parts. First, the cluster's centers of gravity are moved onto the axes, following, the signal space is distorted. Assuming that a and b are the original parameters of the straight line and α is the rotation angle, $f_k(\cdot)$ has to be applied with the transformed parameters

$$b' = \frac{b \cdot \cos(\alpha) - \sin(\alpha)}{\cos(\alpha) + b \cdot \sin(\alpha)}, \quad a' = a \cdot (\cos(\alpha) - b' \cdot \sin(\alpha))$$

(Eq.44)

15

153157 Besides the two EPOC algorithms explained above section, different algorithms can be designed that will, however, most likely exhibit a higher degree of computational complexity.

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ABSTRACT

5 A method and an apparatus relate to a fine frequency syn-
chronization compensating for a carrier frequency deviation
from an oscillator frequency in a multi-carrier demodulation
system of the type capable of carrying out a differential
phase decoding of multi-carrier modulated signals, the sig-
nals comprising a plurality of symbols, each symbol being
10 defined by phase differences between simultaneous carriers
having different frequencies. A phase difference between
phases of the same carrier in different symbols is deter-
mined. Thereafter, a frequency offset is determined by
eliminating phase shift uncertainties related to the trans-
15 mitted information from the phase difference making use of a
M-PSK decision device. Finally, a feedback correction of the
carrier frequency deviation is performed based on the deter-
mined frequency offset. Alternatively, an averaged frequency
offset can be determined by averaging determined frequency
20 offsets of a plurality of carriers. Then, the feedback cor-
rection of the frequency deviation is performed based on the
averaged frequency offset.

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